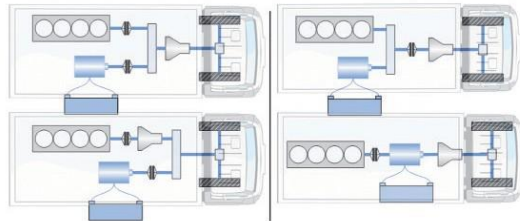
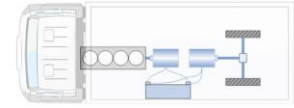


MORPHEE HEAVY DUTY VEHICLE SIMULATION ON ENGINE TEST BED

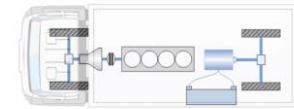
AUTOMATION



Parallel hybrid



Serial hybrid



Parallel hybrid dissociated on the two final drive



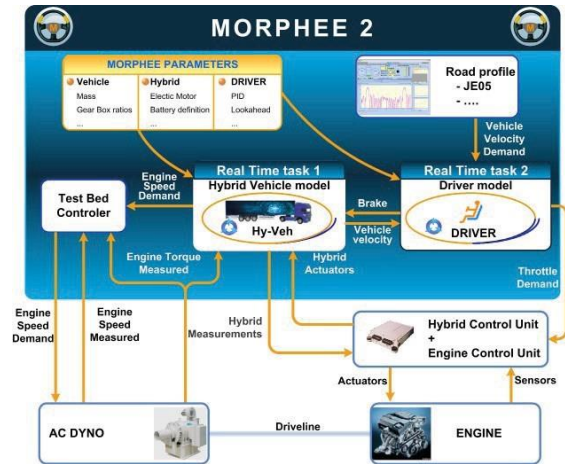
» Reduce your costs and time of engine development by performing the vehicle tests on engine test bed.

FEV offers a MORPHEE application which enables to simulate the automotive vehicle dynamics and its driver in real-time on the engine test bed. This application enables to accurately reproduce the certification procedure for vehicle test bed directly on the engine test bed. Thus, it accelerates the engine development by reducing the need to wait for the availability of the vehicle prototype.



- » Available for Conventional and Hybrid Electric Vehicles
- » Reproduction of the vehicle dynamics directly on the engine test bed
- » Reduced operating costs as compared to vehicle test bed
- » Customizable models, calculation algorithms and test procedures
- » Numerous standard test procedures available
- » Automatic calculation of pollutant emissions for gaseous pollutants during the test

MORPHEE HEAVY DUTY VEHICULE SIMULATION ON ENGINE TEST BED

» Reduce your costs and time of engine development by performing the vehicle tests on engine test bed.



Technical Data

Simulated elements	
Driver	Controls the pedals position (accelerator, clutch and brake) and the gear switching management for manual gear box.
Standard	Real-time driver 10 to 100 Hz control based on PI approach
Look Ahead	Real-time driver 10 Hz control integrating anticipation on vehicle velocity demand and feed forward term
Vehicle	Simulate the vehicle dynamic
Conventional	Real-time models 500 Hz to 1 kHz, for vehicle with manual or automatic gear box
Hybrid Electric Vehicle	Real-time models 500 Hz to 1 kHz, for Serial Parallel hybrid architectures
Gear box	Simulate the gear box
Manual Gear Box	Real-time model 500 Hz to 1 kHz with clutch slip modeling
Automatic gear Box	Real-time model 500 Hz to 1 kHz with torque converter and lockup clutch slip modeling integrating gear switching control.
Electric motor	Two models to simulate the Electric motor and the SSG. Real-time model 100 Hz
Battery	Real-time model 100 Hz
Function modes	
Road Load Simulation/ Accelerator pedal	Manual control of the accelerator pedal. Manual or automatic gear control.
Road Load Simulation/ Vehicle velocity	Manual control of vehicle velocity demand. Accelerator pedal controlled by simulation. Manual or automatic gear control.
Dynamics tests	Execution of timed tests either with fixed gear or with automatic gear shifting
Test procedures (Add-in)	
European	 WHVC
Japanese	 JE05
Performance	1,000 m from rest, 0-100 km/h, ...
Customizable	Test procedure defined by the user
Emission calculations (Add-in)	
Mass[g] and Specific[g/km] emissions from raw exhaust gas	NOx, CO, CO2, HC, CH4 and NMHC on test procedures, calculations according to ISO16183 and UNECE R49 rev 4 and Japan Blue Book Edition 2011 Regulation
Mass[g] and Specific[g/km] emissions from diluted exhaust gas	NOx, CO, CO2, HC, CH4 and NMHC on test procedures, calculations according to UNECE R49 rev4 and Japan Blue Book Edition 2011 Regulation.

Technical Specifications may be modified without prior notice. FEV-D5035-2016-MDS_HD